



Graph Traversals

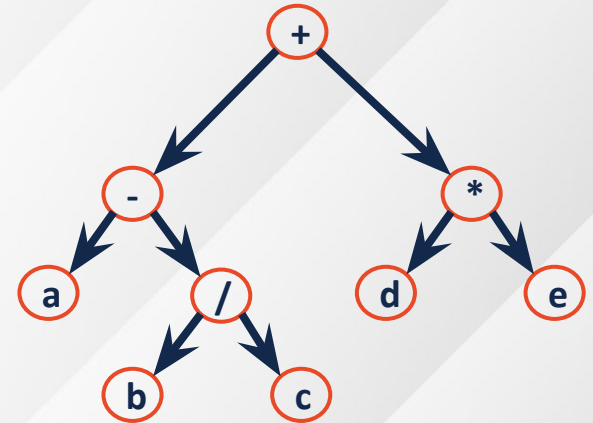
Learning Objectives

1. Implement BFS for Graph Traversals



Level Order Traversal

```
1  template<class T>
2  void BinaryTree<T>::levelOrder(TreeNode * root) {
3      std::queue<TreeNode *> q;
4      q.push(root);
5      while(!q.empty){
6          TreeNode* n = q.front();
7          q.pop();
8          if(n){
9              std::cout << n->data;
10             q.push(n->left);
11             q.push(n->right);
12         }
13     }
14 }
15
```



Graph Traversal - BFS

```
1 BFS(G) :  
2   Input: Graph, G  
3   Output: A labeling of the edges on  
4           G as discovery and cross edges  
5  
6   foreach (Vertex v : G.vertices()):  
7       setLabel(v, UNEXPLORED)  
8   foreach (Edge e : G.edges()):  
9       setLabel(e, UNEXPLORED)  
10  foreach (Vertex v : G.vertices()):  
11      if getLabel(v) == UNEXPLORED:  
12          BFS(G, v)
```

Discovery Edge

- An edge taken to find a new node

Cross Edge

- An edge taken to find an already visited node



Graph Traversal - BFS from a vertex

```
14 BFS(G, v):
15     Queue q
16     q.enqueue(v)
17
18     while !q.empty():
19         v = q.dequeue()
20         If (getLabel(v) != VISITED){
21             setLabel(v, VISITED)
22             foreach (Vertex w : G.adjacent(v)):
23                 if getLabel(w) == UNEXPLORED:
24                     setLabel(v, w, DISCOVERY)
25                     setLabel(w, VISITED)
26                     q.enqueue(w)
27                 elseif getLabel(v, w) == UNEXPLORED:
28                     setLabel(v, w, CROSS)
29         }
```

Node Labels

- Visited
- Unexplored

Edge Labels

- Discovery
- Cross
- Unexplored